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Safety Guidelines

This manual contains notices you have to observe in order to ensure your personal safety, as well as to prevent damage to property. The notices referring to your personal safety are highlighted in the manual by a safety alert symbol, notices referring only to property damage have no safety alert symbol. These notices shown below are graded according to the degree of danger.

A DANGER

indicates that death or severe personal injury will result if proper precautions are not taken.

▲ WARNING

indicates that death or severe personal injury may result if proper precautions are not taken.

ACAUTION

with a safety alert symbol, indicates that minor personal injury can result if proper precautions are not taken.

CAUTION

without a safety alert symbol, indicates that property damage can result if proper precautions are not taken.

NOTICE

indicates that an unintended result or situation can occur if the corresponding information is not taken into account.

If more than one degree of danger is present, the warning notice representing the highest degree of danger will be used. A notice warning of injury to persons with a safety alert symbol may also include a warning relating to property damage.

Qualified Personnel

The device/system may only be set up and used in conjunction with this documentation. Commissioning and operation of a device/system may only be performed by **qualified personnel**. Within the context of the safety notes in this documentation qualified persons are defined as persons who are authorized to commission, ground and label devices, systems and circuits in accordance with established safety practices and standards.

Prescribed Usage

Note the following:

A WARNING

This device may only be used for the applications described in the catalog or the technical description and only in connection with devices or components from other manufacturers which have been approved or recommended by Siemens. Correct, reliable operation of the product requires proper transport, storage, positioning and assembly as well as careful operation and maintenance.

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Disclaimer of Liability

We have reviewed the contents of this publication to ensure consistency with the hardware and software described. Since variance cannot be precluded entirely, we cannot guarantee full consistency. However, the information in this publication is reviewed regularly and any necessary corrections are included in subsequent editions.

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Preface

Preface

Purpose of the manual

This manual supplements the *ET 200S Distributed I/O System* Operating Instructions. General functions for the ET 200S are described in the *ET 200S Distributed I/O System* Operating Instructions.

The information in this document along with the operating instructions enables you to commission the ET 200S.

Basic knowledge requirements

To understand these operating instructions you should have general knowledge of automation engineering.

Scope of the manual

This manual applies to this ET 200S module. It describes the components that are valid at the time of publication.

Recycling and disposal

Thanks to the fact that it is low in contaminants, this ET 200S module is recyclable. For environmentally compliant recycling and disposal of your electronic waste, please contact a company certified for the disposal of electronic waste.

Additional support

If you have any questions relating to the products described in these operating instructions, and do not find the answers in this document, please contact your local Siemens representative.

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Properties

1.1 2AI U HS analog electronic module (6ES7134-4FB52-0AB0)

Properties

- 2 inputs for measuring voltage
- Input ranges:
 - ± 10 V, resolution 15 bit + sign
 - ± 5 V, resolution 15 bit + sign
 - ± 2.5 V, resolution 14 bit + sign
 - 1 to 5 V, resolution 15 bit
- Isolated from the load voltage L+
- Permitted common mode voltage 35 VACss
- Supports isochronous operation
 - Minimum time for the isochronous DP cycle (T_{DPmin}): 250 μs
 - Minimum conversion time of the input modules (T_{WE}): 100 μs
- Firmware update of electronic module is possible.

Note

Inputs must not be connected in parallel for the voltage measurement.

If the non-isolated sensor is connected to the 2AI U HS electronic module, the evaluation of diagnostics (wire break) may not work properly.

1.1 2AI U HS analog electronic module (6ES7134-4FB52-0AB0)

General terminal assignment

Note

Terminals 4, 8, A4, A8, A3 and A7 are only available at specified terminal modules.

	Terminal assignment for 2AI U HS (6ES7134-4FB52-0AB0)													
Terminal	Assignment	Terminal	Assignment	Notes										
1	M ₀₊	5	M ₁₊	M _{n+} : Input signal "+", Channel n										
2	M ₀₋	6	M ₁ -	M _{n-} : Input signal "-", Channel n										
3	M _{ana}	7	M _{ana}	Mana: Ground of the module										
4	n.c.	8	n.c.	n.c.: Not connected (max. 30 VDC can be connected)										
A4	AUX1	A8	AUX1	 AUX1: Protective-conductor terminal or potential bus (freely usable up to 230 VAC) 										
A3	AUX1	A7	AUX1	up to 200 V/(0)										

Usable terminal modules

	Usable terminal modules for 2AI U HS (6ES7134-4FB52-0AB0)										
TM-E15C26-A1 (6ES7193-4CA50- 0AA0)	S7193-4CA50- (6ES7193-4CA30- (6ES7193		TM-E15C23-01 (6ES7193-4CB10- 0AA0)	Spring terminal							
TM-E15S26-A1 (6ES7193-4CA40- 0AA0)	TM-E15S24-A1 (6ES7193-4CA20- 0AA0)	TM-E15S24-01 (6ES7193-4CB20- 0AA0)	TM-E15S23-01 (6ES7193-4CB00- 0AA0)	Screw-type terminal							
TM-E15N26-A1 (6ES7193-4CA80- 0AA0)	TM-E15N24-A1 (6ES7193-4CA70- 0AA0)	TM-E15N24-01 (6ES7193-4CB70- 0AA0)	TM-E15N23-01 (6ES7193-4CB60- 0AA0)	Fast Connect							
00 105 00 206 00 307 00 408 408 408 408	00 10 05 00 20 06 00 30 07 AUX1 40 0A 40 08	00 105 00 206 00 307 00 408	00 105 00 206 00 307	Wiring examples M+ V M+ V M- M- PE (AUX1)							

Block diagram

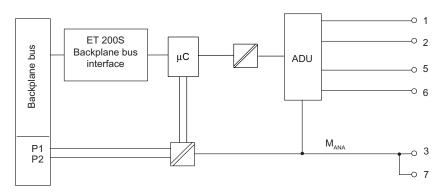


Figure 1-1 Block diagram of the 2AI U HS

Technical specifications for 2AI U HS (6ES7134-4FB52-0AB0)

Dimensions	and weight
Width (mm)	15
Weight	Approx. 40 g
Module-sp	pecific data
Supports isochronous operation	Yes
Supports I&M functions	Yes
Number of inputs	2
Cable length	
Shielded	Max. 200 m
Parameter length	12 bytes
	(4 bytes when used as 6ES7134 4FB50-0AB0)
Address space	4 bytes
Voltages, curre	ents, potentials
Rated load voltage L+ (from the power module)	24 VDC
Reverse polarity protection	Yes
Galvanic isolation	
Between the channels and backplane bus	Yes
 Between the channels and load voltage L+ 	Yes
Between the channels	No
Permissible potential difference	
 Between the inputs and M_{ANA} (U_{CM}) 	35 VAC _{SS}
 Between M_{ANA} and the central grounding point (U_{ISO}) 	75 VDC / 60 VAC
Insulation tested	500 VDC
Current consumption	
 Power supply and load voltage L+ (no load) 	Max. 130 mA
Power dissipation of the module	2 W
Status, interrup	ots, diagnostics
Interrupts	
Hardware interrupt	Can be assigned parameters ¹
Diagnostics function	
Group error display	Red "SF" LED
Diagnostic information can be displayed	Possible ²

1.1 2AI U HS analog electronic module (6ES7134-4FB52-0AB0)

Analog valu	Analog value generation									
Measuring principle	SAR (Successive Appro	ximation Register)								
Cycle time/resolution:										
 Conversion time in μs (per channel) 	15									
Cycle time in ms (per module)	0,25									
Resolution (including overrange)	± 10 V/15 bit + sign									
	± 5 V/15 bit + sign									
	± 2.5 V/14 bit + sign									
	1 to 5 V/15 bit									
Suppression of inter	ference, limits of error									
• Common mode interference (U _{cm}) < 35 VSS)	> 70 dB									
Crosstalk between the inputs	< 50 dB									
Operational limit	± 0,3 % ³									
(in the entire temperature range, with reference to the input range)										
Basic error limit (operational limit at 25°C with reference to input range)	± 0,2 % ³									
Temperature error (with reference to the input range)	± 0.01 %/K ³									
Linearity error (with reference to the input range)	± 0,03 % ³									
Repeatability	± 0,1 % ³									
(in steady state at 25 °C with reference to input										
range)										
Data for sele	cting a sensor									
Input ranges (rated value)/input resistance										
 Voltage 	\pm 10 V/min. 120 k Ω									
	± 5 V/min. 120 kΩ									
	± 2.5 V/min. 120 kΩ									
	1 - 5 V/min. 120 kΩ									
Maximum input voltage for voltage input (destruction limit)	35 V continuous									
Connection of the sensors										
For measuring voltage	Supported									
Smoothing of the measured values	Yes, can be assigned pa means of digital filtering	arameters in 4 steps by								
	Step	Time constant								
	None	1 x cycle time								
	Weak	4 x cycle time								
	Medium	16 x cycle time								
	Strong	32 x cycle time								
 For interface modules with process interrupt capa Parameter assignment error Violation of lower limit value Violation of upper limit value Open circuit (only with 1 V to 5 V) Process interrupt lost 										
³ These values are doubled for measurement range	je ± 2.5 V									

Firmware update

To add functions and for troubleshooting, it is possible to load firmware updates to the operating system memory of the electronic module using STEP 7 HW Config.

Note

When you launch the firmware update, the old firmware is deleted. If the firmware update is interrupted or canceled, the electronic module will no longer be capable of functioning. Restart the firmware update and wait until it has completed successfully.

Note

If the ET 200S is operated in conjunction with an S7-300 CPU with PROFIBUS DP interface or an ET 200S Interface Module IM151-3 PN HIGH SPEED, a station failure of the ET 200S can occur during the firmware update.

I&M functions and firmware update

The interface modules identified in the table below (as of order number) can be used to read and write I&M data from the module and for the firmware update.

Interface module	as of order number
IM151-1 HIGH FEATURE	6ES7151-1BA02-0AB0
IM151-3 PN	6ES7151-3AA22-0AB0
IM151-3 PN HIGH FEATURE	6ES7151-3BA22-0AB0
IM151-3 PN FO	6ES7151-3BB22-0AB0
IM151-7 CPU	6ES7151-7AA20-0AB0

1.2 Compatibility with the predecessor module

1.2 Compatibility with the predecessor module

Compatible with 2AI U HS analog electronic module (6ES7134-4FB51-0AB0 / 6ES7134-4FB50-0AB0)

If you configure the 2AI U HS (6ES7134-4FB52-0AB0) as the predecessor module (6ES7134-4FB51-0AB0/ 6ES7134-4FB50-0AB0), it behaves compatibly.

The following technical specifications of the 2AI U HS (6ES7134-4FB52-0AB0) are set according to the predecessor module (6ES7134-4FB51-0AB0/ 6ES7134-4FB50-0AB0):

Technical specifications for 2AI U HS 6ES7134-4FB52-0AB0		configured as 6ES7134-4FB51-0AB0/ 6ES7134-4FB50-0AB0					
Analog value generation							
Cycle time in ms (per module)	0.25 ms	1 ms					
Resolution (including overrange)	± 10 V/15 bit + sign	± 10 V/13 bit + sign					
	± 5 V/15 bit + sign	± 5 V/13 bit + sign					
	± 2.5 V/14 bit + sign	± 2.5 V/13 bit + sign					
	1 to 5 V/15 bit	1 V to 5 V/13 bits					
	Sensor selection data						
Smoothing of the measured values	Time constant	Time constant					
	1 x cycle time	1 x cycle time					
	4 x cycle time	64 x cycle time					
	16 x cycle time	128 x cycle time					
	32 x cycle time	512 x cycle time					

Current consumption and power loss

Note the change in the values for current consumption, power loss, common mode voltage, and destruction limit of the 2AI U HS (6ES7134-4FB52-0AB0) compared to the predecessor module (6ES7134-4FB51-0AB0/ 6ES7134-4FB50-0AB0).

Parameters

2.1 Parameters

Table 2-1 Parameters for analog input module

2AI U HS	Range of values	Default setting	Applicability
Group diagnostics (parameter	Disable	Disable	Module
assignment error, internal error)	Enable		
Diagnostics: Overflow/underflow	Disable	Disable	Module
	Enable		
Diagnostics: Wire break at 1 to 5 V	Disable	Disable	Channel
	Enable		
Smoothing	• None	None	Channel
	 Weak 		
	Medium		
	Strong		
Hardware interrupt enable	Disable	Disable	Module
	Enable		
Type/range of measurement	 Deactivated 	± 10 V	Channel
	• ± 2,5 V		
	• ±5V		
	• ± 10 V		
	• 1 mA to 5 V		
High limit	low to high limit of the overrange	Depending on the measuring range	Channel
Low limit	Low to high limit of the nominal range	Depending on the measuring range	Channel

Note

If you deactivate a channel of the electronic module, you do not gain any advantages in terms of speed due to the measuring procedure.

2.2 Parameter description

Smoothing

The individual measured values are smoothed by digital filtering. The smoothing can be adjusted in four steps, in which the smoothing factor k multiplied by the cycle time of the electronic module equals the time constant of the smoothing filter. The higher the smoothing, the greater the time constant of the filter.

The following diagrams show the step response with the various smoothing factors depending on the number of module cycles.

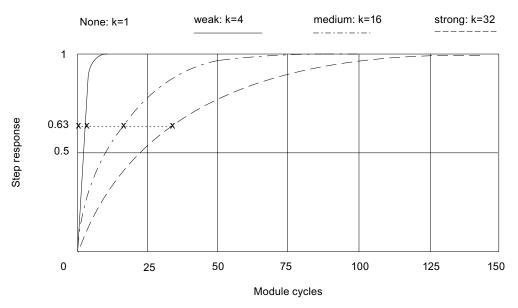


Figure 2-1 Smoothing for 2AI I 2WIRE HS (as of 6ES7134-4GB52-0AB0)

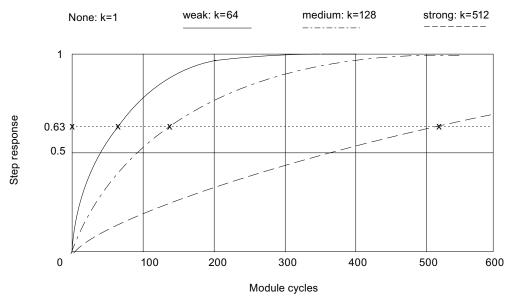
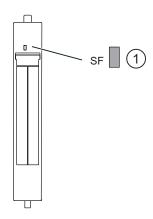


Figure 2-2 Smoothing for 2AI I 2WIRE HS (6ES7134-4GB51-0AB0)

Diagnostics

3.1 Diagnostics using LED display

LED display



① Batch error (red)

Status and error displays

Event (LED)	Cause	Remedy				
SF						
On	No configuration or incorrect module plugged in. No load voltage.present There is a diagnostic message.	Check the parameter assignment. Check the load voltage. Evaluate the diagnostics.				

3.2 Error types

Analog input module error types

Table 3-1 Error types

	Error type	Meaning	Remedy
31 _D	11111: Channel temporarily unavailable	The firmware is being updated. Channel 0 applies to the entire module. The module does not perform any measurements during this time.	
22 _D	10110: Hardware interrupt lost	A hardware interrupt was not detected.	Correction or coordination of the program, process, module
16 _D	10000: Parameter assignment error	Module cannot use the parameter for the channel: Inserted module does not match the configuration. Faulty parameter assignment.	Correct the configuration (align actual and preset configuration). Correct the parameter assignment (diagnostics wire break configured for the permitted measuring range only).
9 _D	01001: Errors	Internal module error (diagnostics message at channel 0 applies to the entire module)	Replace the module.
8 D	01000: Low limit fallen below	Value is below the underrange.	Correct the module/actuator tuning.
7 _D	00111: High limit exceeded	Value is above the overrange.	Correct the module/actuator tuning.
6 _D	00110: Open circuit	Line to the encoder is interrupted.	Correct the process wiring.

3.3 Interrupts

Hardware interrupt of analog input modules

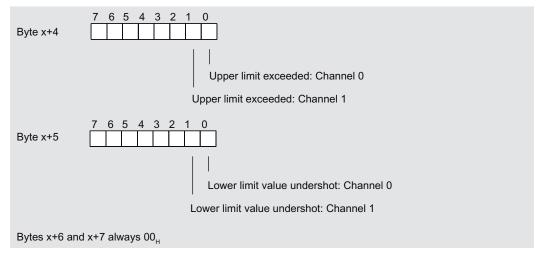


Figure 3-1 Structure as of Byte x+4 and Byte x+5 for hardware interrupt (analog input)

3.3 Interrupts

Analog value representation

4

4.1 Introduction

Electronic modules with analog outputs

With the electronic module with analog inputs, continuously variable signals, such as those occurring in temperature measurement and resistance measurement, can be acquired, evaluated, and converted to digital values for further processing.

4.2 Analog value representation for measuring range with SIMATIC S7

Analog value representation

With the same nominal range, the digitized analog value is the same for input and output values. Analog values are represented in two's complement.

The following table shows the analog value representation for the analog electronic modules.

Table 4-1 Analog value representation (SIMATIC S7 format)

Resolution	Analog value															
Bit number	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
Significance of the bits	S	214	213	212	211	210	2 ⁹	28	27	2 ⁶	2 ⁵	24	23	2 ²	2 ¹	20

Sign

The sign (S) of the analog value is always in bit number 15:

- "0" → +
- "1" → -

4.3 Measuring ranges

Analog values

The following table shows the representation of the binary analog values and the corresponding decimal and hexadecimal representation of the units of the analog values.

The table below shows the 11, 12, 13, 14, and 15 bit resolutions + sign. Each analog value is entered left aligned in the ACCU. The bits marked with "x" are set to "0".

Table 4-2 Analog values (SIMATIC S7 format)

Resolution in bits	Units		Analog value			
	Decimal	Hexadecimal	High byte	Low byte		
11+S	16	10н	8000000	0 0 0 1 x x x x		
12+S	8	8н	8000000	0 0 0 0 1 x x x		
13+S	4	4 _H	8000000	0 0 0 0 0 1 x x		
14+S	2	4н	8000000	000001x		
15 + sign	1	1н	8000000	0000001		

4.3 Measuring ranges

Introduction

The following tables contain the digitized analog values for the measuring ranges of the analog input modules.

Since the binary representation of the analog values is always the same, these tables contain only a comparison of the measuring ranges with the units.

Measuring ranges for voltage ± 2.5 V, ± 5 V and ± 10 V

Table 4-3 SIMATIC S7 format: Measuring ranges \pm 2.5 V, \pm 5 V and \pm 10 V

Measuring range	Measuring range	Measuring range	Units		Range
± 2.5 V	± 5 V	± 10 V	Decimal	Hexadecimal	
> 2,9397	> 5,8794	> 11,7589	32767	7FFF _H	Overflow
2,9397	5,8794	11,7589	32511	7EFF _H	
:	:	:	:	:	Overshoot range
2,5001	5,0002	10,0004	27649	6С01н	
2,5	5,00	10,00	27648	6С00н	
1,86	3,75	7,50	20736	5100н	
:	:	:	:	:	Rated range
-1,86	-3,75	-7,50	-20736	AF00н	
-2,50	-5,00	-10,00	-27648	9400н	
-2,5001	-5,0002	-10,0004	-27649	93FF _н	
:	:	:	:	:	Undershoot range
-2,9397	-5,8796	-11,759	-32512	8100н	
< -2,9397	< -5,8796	< -11,759	-32768	8000н	Underflow

Voltage measuring ranges: 1 mA to 5 V

Table 4-4 SIMATIC S7 format: Measuring range 1 V to 5 V

Measuring range	ι	Units		
1 V to 5 V	Decimal	Hexadecimal		
> 5,704	32767	7FFF _H	Overflow	
5,704	32511	7EFF _H		
:	:	:	Overrange	
5,00014	27649	6С01н		
5,000	27648	6С00н		
4,000	20736	5100н		
:	:	:	Rated range	
1,000	0	0н		
0,99986	-1	FFFF _H		
:	:	:	Undershoot range	
0,296	-4864	ED00 _H		
< 0,296	-32768	8000н	Underflow	

Measured values in the event of a wire break as a function of enabled diagnostics

The following additional information applies to the voltage measuring range 1 to 5 V:

Table 4-5 Measured values in the event of a wire break as a function of enabled diagnostics

Format	Parameter assignment ¹	meter assignment ¹ Measured values		Explanation		
		Decimal	Hexadecimal			
S7	"Wire break" diagnostics enabled	32767	7FFF _H	"Open circuit" diagnostic message		
	 "Wire break" diagnostics disabled "Overflow/underflow" diagnostics enabled 	-32767	8000 _H	 Measured value after leaving the underrange "Low limit fallen below" diagnostic message 		
	"Wire break" diagnostics disabled"Overflow/underflow" diagnostics disabled	-32767	8000 _H	Measured value after leaving the underrange		

4.4 Effect on analog value representation

4.4.1 Effect of the supply voltage and the operating state on analog input values

The input values of the analog modules are dependent on the supply voltage for electronics/encoders and on the operating state of the PLC (CPU of the DP master). The table below shows this dependency..

Table 4-6 Dependence of the analog input values on the operating state of the PLC (CPU of the DP master) and the supply voltage L+

Operating state of the PLC (CPU of the DP master)		Power supply L+ on ET 200S (power module)	Input value of the electronics module with analog inputs (evaluation possible on the CPU of the DP master)		
POWER ON RUN L+ present		L+ present	Process values		
			7FFF _H until first conversion after startup, or after assignment of parameters for the module is completed.		
		L+ missing	7FFF _H		
POWER ON	STOP	L+ present	Process value		
		L+ missing	7FFF _H		
POWER OFF	-	L+ present	-		
		L+ missing	-		

4.4.2 Effect of the value range on the 2AI U HS analog input

The response of the electronics modules with analog inputs depends on the part of the value range in which the input values are located. The table below shows this dependency..

Table 4-7 Response of the analog modules, depending on the location of the analog input value in the range of values

Measured value within	Input value in SIMATIC S7 format	Input value in SIMATIC S5 format
Rated range	Measured value	Measured value
Over-/Undershoot range	Measured value	Measured value
Overflow	7FFF _H	End of the overshoot range +1 plus overflow bit
Underflow	8000 _H	End of the undershoot range -1 plus overflow bit
Prior to parameter assignment, or incorrect parameter assignment	7FFF _H	7FFF _H

Connecting

5.1 Connecting measuring sensors

Introduction

You can connect encoders with voltage signals to the 2AI U HS analog input module.

In this chapter you will find out how to connect the measuring sensors and what to watch for when doing so.

Lines for analog signals

You should use shielded and twisted-pair lines for the analog signals. This reduces the effect of interference. You should ground the shield of the analog lines at both ends of the line. If there are differences in potential between the ends of the line, a compensating current flows via the shield that can interfere with the analog signals. If this is the case, you should only ground the shield at one end of the line.

Analog input modules

The analog input modules are galvanically isolated:

- Between logic and backplane bus
- Between load voltage and the channels There is no connection between M_{ANA} and the central grounding point.

Note

Ensure that this difference in potential U_{ISO} does not exceed the permitted value. If there is a possibility of exceeding the permitted value, make a connection between terminal M_{ANA} and the central grounding point.

Connecting measuring encoders to analog inputs

Between the measuring lines M- of the input channels and the reference point of the measuring circuit M_{ANA} there can be only a limited potential difference U_{CM} (common-mode voltage). To ensure that the permitted value is not exceeded, you must take different steps depending on the whether the sensors are isolated or non-isolated. The steps you have to take are described in this chapter.

5.1 Connecting measuring sensors

Abbreviations used

The meanings of the abbreviations in the figures below are as follows:

M + Measuring line (positive)

M - Measuring line (negative)

M_{ANA} Analog measuring circuit reference potential

M Frame connection

L + Rated load voltage 24 VDC

U_{CM} Potential difference between inputs and reference potential of the measuring

circuit MANA

U_{ISO} Potential difference between M_{ANA} and central grounding point

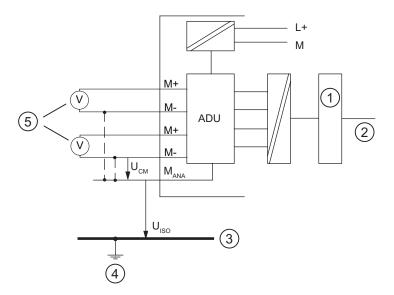
Isolated measuring sensors

The isolated measuring sensors are not connected to the local ground potential. They can be floating. Depending on local conditions or interference, potential differences U_{CM} (static or dynamic) can occur between the measuring lines M- of the input channels and the reference point of the measuring circuit M_{ANA} .

To ensure that the permitted value for U_{CM} is not exceeded in environments with strong EMC interference, the following applies:

For the 2 Al U analog input module: Connect M- with MANA!

The following figure illustrates the connection of isolated measuring sensors to the floating analog input modules.



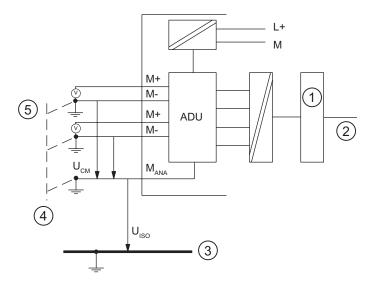
- ① Logic
- ② Backplane bus
- ③ Ground bus
- ④ Central grounding point
- ⑤ Isolated measuring sensors

Non-isolated measuring sensors

The non-isolated measuring sensors are connected to the local ground potential. You must connect M_{ANA} to the ground potential. Depending on local conditions or interference, potential differences U_{CM} (static or dynamic) can occur between the locally distributed measuring points.

If the permitted value for U_{CM} is exceeded, there must be equipotential bonding conductors between the measuring points.

The following figure illustrates the connection of non-isolated measuring sensors to a floating analog input module.



- ① Logic
- ② Backplane bus
- 3 Ground bus
- ④ Equipotential bonding cable
- ⑤ Non-isolated measuring sensors

Sensor selection

Note the following factors when selecting the sensors:

- Length, impedance, and capacitance of the cable
- · Reaction speed of the utilized sensors

5.2 Wiring unused channels of the analog input modules

5.2 Wiring unused channels of the analog input modules

Rules

Pay attention to the following instructions when wiring unused channels:

- "Disable" unused input channels when setting parameters.
- A disabled channel always returns the value 7FFF_H.
- The cycle time remains unchanged at 250 µs.
- If there are unused channels, you must wire the jumpers on the terminal module:

Analog input module	TM connection terminal							
	Channel 0			Channel 1				
	1	2	3	4	5	6	7	8
2AI U HS	• • •		• • •					

5.3 Using the shield connection

Rules

To prevent interference we recommend the following with the analog electronic modules:

- Use shielded wires to the sensors and actuators.
- Lay out the wire shields on the shield connection.
- Connect the shield connection with low impedance to the ground bus.

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