SIEMENS

SIMATIC 505

Isolated Interrupt Discrete Input Modules

User Manual

Order Number: PPX:505–8123–2 Manual Assembly Number: 2586546–0085 Second Edition

DANGER

DANGER indicates an imminently hazardous situation that, if not avoided, will result in death or serious injury.

DANGER is limited to the most extreme situations.

WARNING indicates a potentially hazardous situation that, if not avoided, could result in death or serious injury, and/or property damage.

CAUTION indicates a potentially hazardous situation that, if not avoided, could result in minor or moderate injury, and/or damage to property.

CAUTION is also used for property-damage-only accidents.

Copyright 1995 by Siemens Industrial Automation, Inc. All Rights Reserved — Printed in USA

Reproduction, transmission, or use of this document or contents is not permitted without express consent of Siemens Industrial Automation, Inc. All rights, including rights created by patent grant or registration of a utility model or design, are reserved.

Since Siemens Industrial Automation, Inc., does not possess full access to data concerning all of the uses and applications of customer's products, we do not assume responsibility either for customer product design or for any infringements of patents or rights of others which may result from our assistance.

MANUAL PUBLICATION HISTORY

SIMATIC 505 Isolated Interrupt Discrete Input Modules User Manual Order Manual Number: PPX:505-8123-2

Refer to this history in all correspondence and/or discussion about this manual.

Event	Date	Description
Original Issue	03/93	Original Issue (2801386–0001)
Second Edition	04/95	Second Edition (2801386–0002)

LIST OF EFFECTIVE PAGES

Pages	Description	Pages	Description
Cover/Copyright	Second Edition		
History/Effective Pages	Second Edition		
iii — vii	Second Edition		
1-1 — 1-3	Second Edition		
2-1 — 2-14	Second Edition		
3-1 — 3-5	Second Edition		
A-1 — A-4	Second Edition		
Registration	Second Edition		

Contents

Preface

3.2

Chapter 1 Product Overview

1.1	Description of Basic Features	1-2
	Module Features	1-2
	Compatibility with SIMATIC CPUs	1-2
	Power Sources	1-2
	Operating Modes	1-2
	Optional Time Constant Filter	1-2
	Physical Features	1-3
	Manual Contents	1-3
Cha	pter 2 Installing the Module	
2.1	Overview of Installation	2-2
	Flow of Tasks	2-2
	Handling the Module	2-3
	Visual Inspection	2-3
~ ~	Configuring the Medule Operating Mede	2.4
Z.Z		2-4
	Selecting Interrupt Type	2-4
	Selecting 10-ms lime-Constant Filter	2-5
	Example Settings	2-6
2.3	Inserting the Module into the Base	2-7
	Inserting the Module	2-7
2.4	Field Wiring	2-8
	Wiring Guidelines	2-8
	Avoiding Noise	2-8
	Sequence of Inputs	2-9
	Wiring the Terminal Block	2-11
	Connecting the Terminal Block	2-12
2.5	Configuring I/O Memory in the CPU	2-14
Cha	pter 3 Operating the Module	
21	Operational Description	2 2
J. I		3-2
	using the Mogule in Non-Interrupt Mode	3-2

	J-Z
Using the Module in Interrupt Mode	3-2
Writing an Interrupt RLL Program	3-3
Basic Outline of Interrupt Processing	3-3
Module Status and Troubleshooting	3-4
Module Status and Troubleshooting LED Array	3-4 3-4
Module Status and Troubleshooting LED Array Troubleshooting	3-4 3-4 3-5

Appendix A Specifications

A.1	Specifications	A-2
A.2	Terminal Block Worksheet	A-4

List of Figures

Figure 1-1	DC Interrupt Input Module	1-3
Figure 2-1	Flowchart of Installation	2-2
Figure 2-2	Location of Interrupt Dipswitch Group	2-4
Figure 2-3	S1 Dipswitch Settings	2-5
Figure 2-4	S2 Dipswitch Settings	2-5
Figure 2-5	Example Interrupt Type Settings	2-6
Figure 2-6	Inserting the Module into the Base	2-7
Figure 2-7	I/O Terminals	2-9
Figure 2-8	Field Input Wiring Examples	2-10
Figure 2-9	Installing the Terminal Block	2-12
Figure 2-10	Terminal Blocks	2-13
Figure 2-11	Sample I/O Module Definition Chart	2-14
Figure 3-1	Interrupt Input Module Faceplate and LED Display	3-4
Figure A-1	Input Terminal Worksheet	A-4

List of Tables

Table 3-1	Logical Points Corresponding to Interrupt Inputs 9 – 16	3-2 2 5
		S-0 ∧ 0
Table A-2	Physical Specifications	A-2 A-2
Table A-3	Electrical/Performance Specifications	A-3

	This manual provides the information needed to install, wire, and configure the following SIMATIC® 505 Isolated Interrupt Discrete Input Modules: PPX:505–4317 24 VDC PPX:505–4318 48 VDC PPX:505–4319 125 VDC Except for their input voltage differences, these modules function identically.
Other Manuals	Refer to the manuals listed below for instructions on installing, programming, and troubleshooting your controller and I/O. The <i>x</i> in the order number refers to the latest edition.
	• SIMATIC 505 Programming Reference Manual (PPX:505–8104–x)
	• <i>SIMATIC</i> [®] <i>525/535 Hardware/Installation Manual</i> (PPX:505–8103– <i>x</i>)
	• <i>SIMATIC</i> [®] 545 System Manual (PPX:545–8101– <i>x</i>)
	• <i>SIMATIC</i> [®] <i>555 System Manual</i> (PPX:555–8101– <i>x</i>)
	• <i>SIMATIC</i> [®] <i>560T/565T System Manual</i> (PPX:560/565–8109– <i>x</i>)
	• <i>SIMATIC</i> [®] 545/555 System Manual (PPX:545/555–8101–x)
	• The user manual for your release of $TISOFT^{\scriptscriptstyleTM}$
Agency Approvals	The Interrupt Input Modules meet the standards of the following agencies:
	• Underwriters Laboratories [®] : UL Listed (Industrial Control Equipment)
	• Canadian Standards Association: CSA Certified (Process Control Equipment)
	• Factory Mutual Approved; Class I, Div. 2 Hazardous Locations
	• Verband Deutscher Elektrotechniker (VDE) 0160 Clearance/Creepage for Electrical Equipment (Self-Compliance)
	Series 505 products have been developed with consideration of the draft standard of the International Electrotechnical Commission Committee proposed standard (IEC-65A/WG6) for programmable controllers (released as IEC 1131–2, Programmable Controllers Part 2: Equipment Requirements and Tests, First Edition, 1992–09). Contact Siemens Industrial Automation, Inc., for a listing of the standards to which Series 505 complies.
Telephoning for Assistance	For technical assistance, contact your Siemens Industrial Automation, Inc. distributor or sales office. If you need assistance in contacting your U.S. distributor or sales office, call 1–800–964–4114.

Chapter 1 Product Overview

1.1	Description of Basic Features	1-2
	Module Features	1-2
	Compatibility with SIMATIC CPUs	1-2
	Power Sources	1-2
	Operating Modes	1-2
	Optional Time Constant Filter	1-2
	Physical Features	1-3
	Manual Contents	1-3

Module Features	The SIMATIC 505 Isolated Interrupt Input Modules have 16 discrete input circuits and operate on different voltages depending on the module. The PPX:505–4317 operates on 24 VDC, the PPX:505–4318 on 48 VDC, and the PPX:505–4319 on 125 VDC. Up to 8 of the 16 points can be configured as interrupt points. Isolation is provided between each point. The modules operate identically except for differences in input voltage. The Interrupt Input Modules are compatible with all Series 505 [™] bases.
Compatibility with SIMATIC CPUs	The Interrupt Input Modules are compatible with all SIMATIC 505 CPUs when used in the non-interrupt mode.
	When interrupt mode is selected for any of the configurable inputs, the module is compatible with the SIMATIC 545 and 555 CPUs with Firmware Release 2.1 (or greater). Consult the release notes or other associated documentation to determine if interrupt mode is supported by a particular CPU.
Power Sources	The Interrupt Input Modules sense incoming DC signals from field devices and operate on power supplied by the I/O base backplane. Refer to your system manual for instructions on supplying power to the system I/O base.
Operating Modes	The Interrupt Input Module can be used in one of the following two modes.
	• 16 isolated discrete inputs, all non-interrupt mode:
	When this module is used in non-interrupt mode, it functions as a standard 16-point discrete input module and can be installed in any base (local or remote) of a Series 505 programmable controller system.
	• Configurable mix of interrupt inputs and non-interrupt inputs:
	When this module is used in interrupt mode, it functions as a 32-point I/O module (16 physical inputs and 16 internal points) and can only be installed in the local base of the system. Local Base is defined as the I/O base containing the CPU.
	Interrupt input mode triggers an immediate response to a field device condition without having to wait for the CPU to complete its program scan cycle.
	You can configure the module to detect transitions from on to off, off to on, or either edge when you select interrupt type for a pair of input points.
Optional Time Constant Filter	An eight-position dipswitch allows you to enable a 10-ms filter on any of the 16 physical input points in groups of two.

- Physical Features The Interrupt Input Modules have two groups of dipswitches located at the top of the board, as shown in Figure 1-1. The module includes a standard input terminal connector which can be detached from the module without having to remove the module from the base. An LED array on the faceplate shows input status for each point and also interrupt enable mode.
- Manual Contents Chapter 2 describes how to configure the dipswitches, wire the terminal block, and install the module.

Chapter 3 describes the basic operating features and the use of the LED array for reading the status of the inputs.



Figure 1-1 DC Interrupt Input Module

Chapter 2 Installing the Module

2.1	Overview of Installation	2-2
	Flow of Tasks Handling the Module Visual Inspection	2-2 2-3 2-3
2.2	Configuring the Module Operating Mode Selecting Interrupt Type Selecting 10-ms Time-Constant Filter	2-4 2-4 2-5
2.3	Inserting the Module into the Base	2-0 2-7 2-7
2.4	Field Wiring Wiring Guidelines Avoiding Noise Sequence of Inputs Wiring the Terminal Block Connecting the Terminal Block	2-8 2-8 2-9 2-11 2-12
2.5	Configuring I/O Memory in the CPU	2-14

2.1 Overview of Installation

Flow of Tasks Figure 2-1 shows the organization of the tasks described in this chapter.



Figure 2-1 Flowchart of Installation

Handling the Module	Many integrated circuit (IC) devices are susceptible to damage by the discharge of static electricity. Follow the suggestions listed below to reduce the probability of damage to these devices when you are handling a CPU, a base controller, or any of the I/O modules.
	Both the module and the person handling the module should be at the same ground potential. To accomplish this, fulfill the following conditions.
	• Transport the module in an anti-static container or antistatic material.
	• Ensure that the work area has a conductive pad with a lead connecting it to a common ground.
	• Ground yourself by making contact with the conductive pad and/or by wearing a grounded wrist strap.
Visual Inspection	If there is any visible damage to the module, contact your Siemens Industrial Automation, Inc. distributor or sales office for replacement.

Selecting Interrupt Type Two groups of dipswitches are located on the top edge of the module facing upward, as shown in Figure 2-2. The set of switches closest to the backplane connector, labeled S1, is the group used to select interrupt type for points 9 through 16.



Figure 2-2 Location of Interrupt Dipswitch Group

The interrupt type is selected for pairs of input points and cannot be selected individually. Each pair of dipswitches in the S1 group selects the interrupt mode for a pair of input points, as listed below.

Switches 1 and 2 control points 9 and 10 Switches 3 and 4 control points 11 and 12 Switches 5 and 6 control points 13 and 14 Switches 7 and 8 control points 15 and 16

You configure each pair of points to detect on-to-off, off-to-on, or either-edge transitions according to the way you set each pair of dipswitches.

NOTE: This section discusses how to set the dipswitches to select interrupt types for the configurable input points. To operate as interrupt inputs, these points must also be enabled individually in the user program using the internal logic outputs assigned to this task. Refer to Chapter 3 for more information.

Figure 2-3 shows how to set the dipswitches in S1 to select the interrupt type for each pair of input points.



Figure 2-3 S1 Dipswitch Settings

Selecting 10-ms Time-Constant Filter The second set of dipswitches, located closest to the faceplate of the module and labeled S2, is used to select input filter time constants of 10 ms per pair of points, as shown in Figure 2-4. You can filter any of the 16 input points, both non-interrupting and interrupting. The 10-ms filter may be useful in applications where relay chatter or switch bounce is a potential problem.

NOTE: Filtering delays module response time to input transitions. For interrupt applications with critical response time requirements, be careful to take into account the time delay before you decide to use these filters.



Figure 2-4 S2 Dipswitch Settings

Example Settings Figure 2-5 shows an example of a configuration that enables interrupt mode and the dipswitch setting used for the given configuration.

- Points 9 and 10 are configured to be non-interrupting.
- Points 11 and 12 are configured to generate an interrupt upon an **on-to-off** transition.
- Points 13 and 14 are configured to generate an interrupt upon an **off-to-on** transition.
- Points 15 and 16 are configured to generate an interrupt upon **either** transition.



Figure 2-5 Example Interrupt Type Settings

NOTE: To operate as interrupt inputs, these points must also be enabled individually in the user program using the internal logic outputs assigned to this task. Refer to Chapter 3 for more information.

	WARNING
	Failure to follow appropriate safety precautions could result in death or serious injury and/or damage to equipment.
	To minimize risk of potential shock hazard, turn off power to the I/O base and to any modules installed in the base before inserting or removing a module or installing a terminal block.
	The power must be turned off to the I/O base and to any modules installed in the base before inserting or removing a module or installing a terminal block.
Inserting the Module	The Interrupt Input Modules are single-wide and may be installed in any available slot for single-wide modules. Do not touch the printed circuit board (PCB) while inserting the module. This could cause electrostatic damage to its components. To insert the module, follow these steps. 1. Position the module so that the front bezel is facing you.
	 Hold the top and bottom of the bezel and slide the module carefully into the slot, pushing it all the way into the base. If you have inserted the module correctly, you will feel a slight increase in resistance as the module mates with the backplane connector. (See Figure 2-6).
	3. Use a flat-head screwdriver to tighten the screws at the top and bottom of the bezel. This grounds the module to the base. Do not overtighten.





Wiring Guidelines	These modules do not require user-supplied power. A module consumes a maximum of 2.0 W of +5 V power from the base backplane.
	The modules have been designed to work with up to 1000 feet (303 meters) of wire to the switch. The size of the wire used must be adequate for switch current. To prevent noise on the signal wiring, keep signal and power wiring separate. For input or output signals and class 2 power supply wires, use shielded, twisted-pair cable (12–26 AWG or 0.16–3.2 mm ² , either stranded or solid-type).
	WARNING
	Use supply wires suitable for at least 75°C. Signal wiring connected to this module must be rated at least 300 V.
	Wiring that does not meet the requirements could cause death and/or serious injury or damage to equipment.
	Ensure that your wire is suitable for at least 75°C, and that signal wiring con- nected to this module is rated at least 300 V.
Avoiding Noise	To minimize unwanted noise, follow these wiring installation guidelines.
	• Use the shortest possible wires.
	Separate discrete and analog wires.
	• Avoid placing signal wires parallel to high-energy wires. If the two must meet, cross them at right angles.
	• Avoid bending the wire into sharp angles.
	• Use wireways for wire routing.
	• When using shielded wires, ground them only at the source end for better noise immunity.
	• Place wires so that they do not interfere with existing wiring.
	• Label the wires.
	NOTE: Terminate shielding for the output cable at the same earth ground as the user power supply. Terminate shielding for the input signal wire at the same earth ground as the transmitter.

Sequence of Inputs

Figure 2-7 shows the sequence of inputs for the modules as well as the input terminal label provided with the module. The right column represents the right row of screws on the terminal block and the left column represents the left row.



Figure 2-7 I/O Terminals

The Interrupt Input Modules inputs are floating. Therefore, the inputs will operate when wired in either a sinking or sourcing configuration, as shown in Figure 2-8.



Figure 2-8 Field Input Wiring Examples

Wiring the Terminal Block	You tern proc	can use either of the terminal blocks shown in Figure 2-10. Both ninal blocks are removable. To wire the terminal block, follow the cedure below.
	1.	Turn the terminal block, with the screw-heads facing you, until the A-series of terminals is at the top and the D series is at the bottom.
	2.	Using Figure 2-7 as a wiring guide, start with the D's and loosen the appropriate terminal block screws.
	3.	Strip back the insulation on the wires about $1/4$ to $3/8$ inch or one centimeter. Use a $12-26$ AWG or a $0.16-3.2$ mm ² metric gauge wire of either stranded or solid type.
		(If you are using the side-accessible connector number 2587705–8010, a spade or a ring lug may be attached to the end of the wire.)
	4.	Connect the end of the wire to the loosened terminal block screw and tighten the screw firmly. Once the D's are completed, connect the C's, and continue until the terminal block is completely wired.
	NO	E: An easy-to-use, stick-on label is provided separately with space

NOTE: An easy-to-use, stick-on label is provided separately with space available to write in the name of each input. Write in the corresponding input names and apply the label to the flat side of the terminal block. Appendix A contains a worksheet to help you document the input labeling. Connecting the Terminal Block To connect the terminal block to the module, follow these steps. (See Figure 2-9.)

- 1. Align the terminal block with the edge card connector on the bezel.
- 2. Press firmly at both ends of the terminal block until it is seated.
- 3. Tighten the screws at the top and bottom. Do not over-tighten.



Figure 2-9 Installing the Terminal Block



Figure 2-10 Terminal Blocks

After the module has been inserted into the I/O base, you must register the I/O addresses for each module in the CPU memory. (The module does not automatically register addresses in the CPU when it is inserted.) This is important because even though the module may appear to be operating correctly, it will not communicate with the CPU unless the module is configured in the I/O map. A programming device must be connected to the CPU to configure the I/O map and verify CPU- to-module communications. Apply power to the base and follow these steps to configure the I/O memory map.

- 1. Access the Configure I/O function menu.
- 2. Select the appropriate channel and base number.
- 3. Execute the Read Base function.

If the module is configured for non-interrupt mode, the module appears as 16 X inputs, as shown in Figure 2-11, slot 1.

If the module is configured for interrupt mode, the module appears as 24 X inputs and 8 Y outputs, as shown in Figure 2-11, slot 2.

4. You need to assign the starting I/O address and write the completed I/O configuration to the controller memory. (In the example for slot 2, the starting address is set for 0017.)

For more information on configuring the I/O, refer to your TISOFT manual.



Figure 2-11 Sample I/O Module Definition Chart

Chapter 3 Operating the Module

3.1	Operational Description	3-2
	Using the Module in Non-Interrupt Mode Using the Module in Interrupt Mode Writing an Interrupt RLL Program Basic Outline of Interrupt Processing	3-2 3-2 3-3 3-3
3.2	Module Status and Troubleshooting	3-4
	LED Array Troubleshooting	3-4 3-5

3.1 Operational Description

Using the Module in Non-Interrupt Mode	If you decide to use the Interrupt Input Modules in an application that do not require interrupt inputs, and you have selected the No Interrupt switch settings for each of the interrupt point pairs, then the module ento Non-interrupt Mode when power is applied to the base.			in an application that does ed the No Interrupt irs, then the module enters e base.
	In tl syst all o	his mode, the mo em and is recogn f which are avail	dule can be installed in any ized by the CPU as having 1 lable for field connection.	base (local or remote) of the .6 discrete input (X) points,
Using the Module in Interrupt Mode	If yo inpu In th cont disc	ou selected an int at points, then th his mode, the mo caining the CPU rete input (X) poi	cerrupt type for at least one of e module enters Interrupt M dule can only be installed in module) and is recognized by ints and 8 discrete output (Y	of the pairs of configurable lode when power is applied. the local base (the I/O base the CPU as having 24) points.
	In I	nterrupt Mode, t	he points are defined as follo	WS.
	•	Points 1 – 8: No	n-interrupting field inputs	
	•	Points 9 – 16: Co inputs based up	onfigurable (interrupting or on the settings of the interru	non-interrupting) field 1pt switches on the module
	•	Points 17 – 24: I module, report t result of a field i one of the interr	Logical (internal) status input to the CPU which point has g input transition. Each of the rupting field inputs, as show	ats that, when set by the generated an interrupt as a se points corresponds to n in Table 3-1.
	•	Points 25 – 32: I for each of the in point enables in shown in Table 3	Logical outputs that act as ir nterrupting field inputs. Tur terrupting operation on the 3-1.	ndividual interrupt enables ning on a given output corresponding input, as
		Table 3-1 Logi	cal Points Corresponding to) Interrupt Inputs 9 – 16
	Р	hysical Input	Logical Interrupt Status	Logical Interrupt Enable

Physical Input Points (X)	Logical Interrupt Status Inputs (X)	Logical Interrupt Enable Outputs (Y)
9	17	25
10	18	26
11	19	27
12	20	28
13	21	29
14	22	30
15	23	31
16	24	32

Writing an Interrupt RLL Program	In o writ logi moo of tl <i>Ma</i> <i>Refe</i>	order to take advantage of the Interrupt feature of this module, you must te a Relay Ladder Logic (RLL) program that contains the appropriate c to execute the required response to interrupts generated by this dule. For a more detailed description of the requirements and operation he interrupt RLL program, refer to the <i>SIMATIC TI545/TI555 System</i> <i>nual</i> (PPX:545/555–8101–2) and the <i>SIMATIC TI505 Programming</i> <i>Berence Manual</i> (PPX:505–8104–5).
Basic Outline of Interrupt Processing	The inte	e Interrupt Input Module and the CPU work together to process errupt signals in the following manner.
J	1.	When a field signal connected to an interrupt input transitions in a manner that matches the interrupt type selected for that input, the module sets the corresponding interrupt status input point and generates an interrupt to the CPU.
	2.	The CPU detects this interrupt, and, if proper qualifying conditions are met, executes the interrupt RLL program, provided the CPU is in Run Mode.
	3.	The CPU automatically issues a rearm signal to the module to clear the current interrupt event and to allow new events.
	4.	If an interrupt transition occurs at a given input point while the CPU is currently processing an interrupt event, the module holds the new event until the CPU issues the rearm signal to complete processing of the current event. The module then generates another interrupt to signal the CPU that a new event has occurred.
	NO is <i>h</i> be l This puls you	TE: If an interrupt transition occurs at an input point while the module <i>olding</i> an event from the <i>same</i> input point, the new event will effectively ost, since the module will only generate a single interrupt to the CPU. s behavior is significant only in pulse-counting applications, where sees could potentially be missed if the pulse frequency is too high. Refer to r CPU's <i>Release Notes</i> for specifications on execution times.

LED Array An LED array showing input and interrupt enable status is located on the front of the module. (See Figure 3-1.)



Figure 3-1 Interrupt Input Module Faceplate and LED Display

The input status LEDs indicate the state of the input from the logic (PLC) side, not from the field side. When an input is on, a corresponding LED turns on.

The interrupt enable LEDs indicate the status of the interrupt enable logical outputs (points 25 - 32), which enable or disable the interrupt operation for input points 9 - 16. Interrupt enable status of points 9 to 16 is indicated by the status of LEDs C5 to C8 and D5 to D8.

These LEDs can be used to check normal module operation as well as to troubleshoot when unexpected results are experienced.

Troubleshooting The LED Input Status Indicators and the CPU indicate whether the module is operating correctly. Table 3-2 shows symptoms, probable causes and corrective actions to take if the module is not operating correctly.

Symptom	Probable Cause	Corrective Action
	Not receiving power	Check power supply and connections.
LED is not lit	User program problem	Check user program or I/O configuration.
	Wrong terminal block connections	Trace wiring connections.
	Faulty LED	Return module for repair.
	Wrong terminal block connections	Trace wiring connections.
Incorrect values	Noise on signal wire exceeding immunity level	Use shielded wire near power wire; check ground wire to base.
	Incorrect or missing configuration	Correctly configure I/O.
Nonfatal error as a result of the module	Module configured incorrectly	Reconfigure the module.

Table 3-2 Troubleshooting Chart

If you cannot correct the problem, contact your Siemens Industrial Automation, Inc. distributor or sales office.

Appendix A Specifications

A.1	Specifications	A-2
A.2	Terminal Block Worksheet	A-4

Operating temperature	0 to 60°C (32 to 140°F)
Storage temperature	-40 to +70°C (-40 to 158°F)
Relative humidity	5% to 95% noncondensing
Pollution degree	2, IEC 664, 664A
Vibration	$\begin{array}{l} \mbox{Sinusoidal} \\ \mbox{IEC 68-2-6, Test Fc} \\ \mbox{0.15 mm peak-to-peak, 10-57 Hz;} \\ \mbox{1.0 g, 57-150 Hz} \\ \mbox{Random} \\ \mbox{IEC 68-2-34, Test Fdc,} \\ \mbox{equivalent to NAVMAT P-9492} \\ \mbox{0.04 g}^2/\mbox{Hz, 80-350 Hz, 3dB/Octave rolloff} \\ \mbox{80 - 20 Hz, 350 - 2000 Hz} \end{array}$
Electrostatic discharge	IEC 801, Part 2, Level 4, (15 kV)
Shock	IEC 68-2-27; Test Ea
Noise immunity, conducted	IEC 801, Part 4, Level 3
Noise immunity on user power lines	MIL STD 461B CS01, CS02, and CS06 per part 4, IEC 255-4, Appendix E; IEEE 472, 2.5 kV; EEC 4517
Noise immunity, radiated	IEC 801, Part 3, Level 3, MIL STD 461B RS01, &RS02
Isolation	1500 Vrms, input-to-controller 1500 Vrms, point-to-point
Corrosion protection	All parts of corrosion-resistant material or plated or painted as corrosion protection

Table A-1	Environmental	Specifications

Table A-2 Physical Specifications

Module type	Series 505 single-wide module
Weight and dimensions of packed module	2 pounds, 15 ounces; $12.75'' \times 13.5'' \times 3.75''$
Weight and dimensions of unpacked module	1 pound, 8 ounces; $10.5'' \times 8'' \times 0.8$
Input signal wiring	Shielded, twisted-pair cable (12–26 AWG or 0.16–3.2 mm ² , either stranded or solid-type)
Spade lug for use with connector 2587705-8010	Amp part number 321462
Ring lug for use with connector 2587705–8010	Amp part number 327891
Minimum torque for bezel screws	2.61 in-lb (0.3 N-m)
Maximum torque for bezel screws	5.22 in-lb (0.6 N-m)

Module	PPX:505-4317	PPX:505-4318	PPX:505-4319
Rated Voltage DC	24	48	125
Input voltage range for ON VDC UH minimum VDC UH maximum	10.0 30.0	43.0 53.0	112.5 137.5
Input voltage range for OFF VDC UL minimum VDC UL maximum	-30.0 3.0	-30.0 10.0	-30.0 25.0
Input current limits during ON mA IH minimum mA IH maximum	2.0 10.0	1.0 6.0	1.0 4.0
Input current for OFF mA maximum	0.5	0.5	0.5
Number of inputs	 16 points in non-interrupt mode (16 Xs) 32 points in interrupt mode (24 Xs, 8 Ys): 16 physical input points (16 Xs) 8 internal logic input points (8 Xs) 8 internal logic output points (8 Ys) 		
Delay time through module	0.5 ms maximum, filter off 10 ms maximum, filter on		
Module power from base	2.0 W maximum (1.6 W typical) at +5 V		

Table A-3 Electrical/Performance Specifications

	AC	Not used
Not used	AR	
Input 1-	A5	Input 1+
input i	A6	Input 2+
Input 2–	A2 A7	Innut 2
Input 3-	A3	input 5+
Input 4_	A8	Input 4+
	BC	Not used
Not used	BR 	Innut 5+
Input 5-	B1	input 5+
Input 6	B2 B6	Input 6+
input 0–	B7	Input 7+
Input 7-	B3 B8	Innut 9
Input 8-	B4	Input o+
		Not used
Not used	C5	Input 9+
Input 9–	C1	Innut 10
nput 10-	C2	input 10+
	C7	Input 11+
nput 11–	C8	Input 12+
nput 12-	C4	· · · · · · · · · · · · · · · · · · ·
Not used	DR	Not used
oput 12	D1 D5	Input 13+
nput 13-	D6	Input 14+
nput 14-	D2	Innut 4E .
nput 15-	D3	input 15+
anut 16	D4	Input 16+
nput 16-		
	Terminal label	

Figure A-1 Input Terminal Worksheet

Customer Response

We would like to know what you think about our user manuals so that we can serve you better. How would you rate the quality of our manuals?

	Excellent	Good	Fair	Poor
Accuracy				
Organization				
Completeness				
Graphics				
Examples				
Overall design				
Size				
Index				

Would you be interested in giving us more detailed comments about our manuals?

□ **Yes!** Please send me a questionnaire.

□ **No.** Thanks anyway.

Your Name:	
Title:	
Telephone Number:	()
Company Name:	
Company Address:	

Manual Name:SIMATIC 505 Isolated Interrupt Discrete Input ModuleEdition:SecondManual Assembly Number:2586546–0085Date:04/95Order Number:PPX:505–8123–2



FOLD

SIMATIC is a registered trademark of Siemens AG.

Series 505 and TISOFT are trademarks of Siemens Industrial Automation, Inc.

Underwriters Laboratories is a registered trademark of Underwriters Laboratories.